#### NeXus Recapitulation and Developments

#### Mark Könnecke

NeXus International Advisory Committee

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- Spends lots of time converting formats or writing readers
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- DA requires N files in different formats, notes, local knowledge
- Cannot read her collaborators data
- Has to keep extra information in yet another form

- Definition of a standard data format
  - Rules
  - Validation tools
- Promotion of NeXus
  - Documentation
  - NeXus API
  - Outreach to the scientific community

- Complete data for typical use
- Extendable, add additional data as you please
- Self describing
- Easy automatic plotting
- Platform independent, public domain, efficient
- Suitable for a wild variety of applications

- 1 Physical file format and API for accessing files
- 2 Rules for storing data in files
- 3 Component and application definitions
- 4 NeXus Utilities



#### Physical File Format

- Portable, self describing, extendable, public domain
- Hierarchical data format, NCSA, HDF-4, later HDF-5
- HDF-5:
  - grouping support
  - on the fly compression
  - reading/writing subsets
  - first dimension appendable
  - Public domain C, F77 access library
  - Used by: NASA, Boing, the weathermen, ....
- XML for those who wish to edit their data



- NeXus-API hides complex HDF API
- Transparent access to all three supported physical file formats
- ANSI-C implementation
- Bindings: F77, Java, SWIG
- January, 4, 2010: 1311217 files processed at PSI alone
- NEW: first class bindings to C++, python, IDL



- Files
- Groups identified by name and a classname beginning with NX
- Scientific data sets
- Attributes
- Links

```
entry:NXentry
sample:NXsample
```

```
instrument:NXinstrument
    source:NXsource
    velocity_selector:NXvelocity_selector
    detector:NXdetector
        data[xsize,ysize], signal=1 (1)
control:NXmonitor
    data
data:NXdata
    link to (1)
```



#### NeXus Processed Data File Structure

```
entry:NXentry
sample:NXsample
processing_name:NXprocess
program
version
parameters:NXparameter
raw_file
data:NXdata
data[nx,ny,nz], signal=1
```



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- Name, classname pair allows for multiple components of the same type
- NXentry allows for multiple datasets in the same file
- NXdata supports automatic plotting
- Take care once when writing, use n times

- Come in all shapes and sizes
- Captured by rules:
  - Store all varied parameters as arrays of length NP at the appropriate place in the NeXus hierarchy
  - For multi detectors, NP, number of scan points is always the first dimension
  - In NXdata: create links to counts and varied variables

```
entry:NXentry
      sample:NXsample
             rotation angle[NP], axis=1 (1)
      instrument:NXinstrument
             detector:NXdetector
                    data[NP], signal=1 (2)
      control:NXmonitor
             data[NP]
      data:NXdata
             link to (1)
             link to (2)
```



#### Scan Example 2: complex scan in Q

```
entry:NXentry
       sample:NXsample
              rotation angle[NP], axis=1 (1)
              phi[NP], axis=1 (2)
              chi[NP], axis=1 (3)
              h[NP], axis=1 (4), primary=1
              k[NP], axis=1 (5)
              [NP], axis=1 (6)
       instrument:NXinstrument
              detector NX detector
                     data[NP], signal=1 (7)
                     polar angle[NP], signal=1 (8)
       data:NXdata
              link to (1)
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              link to (2)
              link to (...)
              link to (8)
```

```
entry:NXentry
      sample:NXsample
             rotation angle[NP], axis=1 (1)
      instrument:NXinstrument
             detector:NXdetector
                    data[NP,xsize,ysize],signal=1 (2)
      control:NXmonitor
             data[NP]
      data:NXdata
             link to (1)
             link to (2)
```



#### Storing Single Data Items

- Units have to specified
- Rules for locating axis



- Polar coordinate system: azimuthal\_angle,polar\_angle, distance
- McStas Coordinate System
- NXgeomtry for enginnering coordinates and describing shapes



### NeXus Component and Application Definitions

- Component definitions: dictionaries of allowed field names for the various NeXus groups
- Application Definitions
  - Define what has to be in a NeXus file for a certain application
  - Defines standards
  - Another view: Contract between file producers and users about what has to be in a NeXus file for a well defined purpose
  - VALIDATION BY NXVALIDATE
- Written in NeXus Definition Language, NXDL

#### NEW: Available NeXus Application Definitions

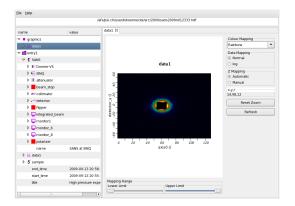
NX ARCHIVE NX REFTOF NX TAS NX TOMOPHASE NX XNB NX TOMOPROC NX INDIRECTOF NX SASTOF NX TOFSINGLE NXMONOPD NXSAS NXTOFRAW NXXEULER NXXROT NXTOFSINGLE NXIQPROC NXSQOM NXXAS NX REFSCAN NX SCAN NX TOMO NX XKAPPA NX IQPROC NX DIRECTOF NX LAUETOF NX LAUETOF NX TOFRAW NX XASPROC



nxbrowse CLI NeXus browser nxtree prints NeXus tree NXmeta dumps all NeXus meta data nxtranslate transforms into NeXus nxvalidate NEW: validates NeXus files nxextract converts from neXus to ASCII and binary nxplot NEW: plots any NeXus file

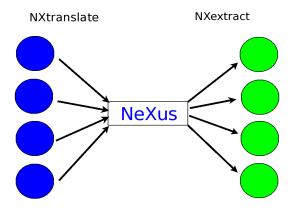


NXplot



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#### NeXus Conversions



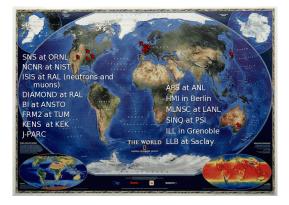


### Other Systems Using NeXus

- DANSE
- DAVE
- FABLE (ESRF)
- ISAW
- LAMP
- openGenie
- ICAT
- Mantid
- openGDA
- All HDF tools



#### Who commits to NeXus?





Challenge 1 in science you are supposed to do new, non standard, things. These of course cannot be easily cast into a standard.



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- Challenge 2 in order to establish a standard a lot of people need to agree
- Challenge 3 a standard requires scarce scientific programming resources for adoption



Chance 1 By using a discoverable data format like NeXus, XML, HDF-5, people can at least figure out what is in the data file.



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Chance 6 Application Definitions



- PanData
- Workshop: HDF5 as hyperspectral data format, January, ESRF
- NeXus workshop at PSI, May
- Upcoming: Data formats for HDR, DESY, end of october



- European initiative for SSO, a shared data file catalog, DA etc
- PanData needs a shared data format in order to make the catalog fly
- Works with NeXus
- Prompted us to have a project plan which we actually executed by now!
- 5.5MM money

- End of January at ESRF, ca 30 participants
- NeXus well received
- Some confusion over a HDF-5 bug in 1.8
- Demand to map imageCIF fully to NeXus in order to benefit from imageCIF ideas
- Missing in NeXus to do full CIF mapping:
  - Scaled data
  - CIF axis specification more accurate
  - Mapping to database concepts

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### NeXus for Synchrotrons

- Workshop at PSI, 10-12 May
- NeXus seen as HDF-5 with NeXus structures, no interest in API
- Requests:
  - NXsubentry
  - Scaled data
  - Simplified hierarchy for experts
  - Indicate image dimensions
  - Tree based higher level API

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- Planned: NeXus is threadsafe when each thread has its own NXhandle
- A little work needs to be done to arrive there
- BUT: HDF-5 serialises access, no performance gain!
- Parallel HDF5, PHDF, with a different API
- PHDF requires: MPI, MPI-IO, parallel file system
- A new NeXus file driver for PHDF would be required
- Will only be implemented when the community really wants it



### Topics for this NIAC Meeting

- 1 Constitution change: NIAC Tech, Chairman
- 2 Choose new officers
- NXsubentry
- 4 Scaled data
- 5 Coordinate systems
- 6 Next project plan
- 7 Simplified hierarchy, NXmeasurement
- 8 Event data
- 9 muSR NeXus

- Observation: we make better progress when working in a smaller group of experts
- Suggestion: Divide NIAC into two entities:
  - Full NIAC: votes officers, ratifies project plans, decides general directions
  - Technical subcommittee: decides technical and implementation details, to be reviewed by full NIAC. Members are selected on merit (contributed work) and approved by full NIAC
- Full NIAC meets only any 2 years: requires extending the terms of officers



- Suggestion: add NXsubentry group below NXentry with the same structure as NXentry
- Multi-method instrument
  - Especially synchrotrons have instruments which combine multiple techniques in one experiment
  - Current NeXus would require separate NXentries for each technique
  - This becomes unnatural with the additional requirement to store multiple experiments in the same file
  - Combining multiple application definitions in one NXentry would cause name collisions
  - The synchrotron people are willing to do the many links NXsubentry requires
- Add application definition compliant NXsubentries to existing files

NXsubentry

entry:NXentry sas,NXsubentry sample:NXsample

```
instrument:NXinstrument
    source:NXsource
    velocity_selector:NXvelocity_selector
    detector:NXdetector
        data[xsize,ysize], signal=1 (1)
control:NXmonitor
    data
data:NXdata
    link to (1)
```

- NeXus stronly suggests storing physical values
- Suggestion: allow scaled data for performance or other reasons
- Implement through additional data attributes
- NeXus stores arrays in C storage order
- Suggestion: allow other orders
- Implement through additional data attributes
- NAPI will not implement the transforms

- transform: This is the indicator that a transformation of the Vraw data is necessary. Transform can have one the following values:
  - power: Vtrue =  $p0 + (Vraw/p1)^{**}p2$
  - logarithmic: Vtrue = p0 +p1\*log(Vraw\*p2)
  - polynomial: Vtrue = p0 + p1\*Vraw + p2\*Vraw\*Vraw + p3\*Vraw\*Vraw\*Vraw ....
- parameters: parameters for calculating Vtrue
- scaled\_units: units after scaling
- direction: a comma separated list of length ndim which specifies for each dimension if it is increasing or decreasing
- precedence: a comma separated list of length ndim which gives the rank order in which array indexes change with respect to other indexes.



- Another look on coordinate systems
- NeXus:
  - Simple, polar coordinates using angles and distances
  - Absolute McStas coordinates using NXgeometry
- imageCIF
  - Arbitrary axis allowed
  - Contains information to build transformation matrices

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### Transformation Matrices

$$T = \left(\begin{array}{rrrrr} 1 & 0 & 0 & x \\ 0 & 1 & 0 & y \\ 0 & 0 & 1 & z \\ 0 & 0 & 0 & 1 \end{array}\right)$$



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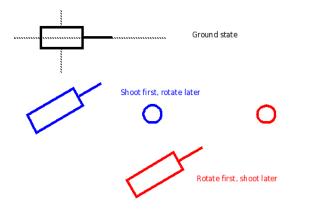
### Transformation Matrices

$$T = \begin{pmatrix} 1 & 0 & 0 & x \\ 0 & 1 & 0 & y \\ 0 & 0 & 1 & z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
$$R = \begin{pmatrix} r11 & r12 & r13 & 0 \\ r21 & r22 & r23 & 0 \\ r31 & r32 & r33 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



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### Combining Transformations



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- Transformations can be combined by matrix multiplications
- Individual matrices can be derived by looking at the situation when everything else is 0
- Absolute positions can be obtained by multiplying the resulting matrix with its transpose
- Defines new coordinate systems at components
- CIF contains a duplication: vector, offset scheme

- Allows to calculate absolute positions of components in the laboratory coordinate systems
- Can directly convert from a detector coordinate system to vectors in Lab coordinate system
- Calculate things like impact of primary beam on detector, SAS
- Allows arbitray axis to be expressed
- Intuitively describe an instrument with angles and translations and still be able to recover absolute coordinates



### type rotation or translation direction vector around which rotated or translated value The angle of rotation or the length of translation dependency The order of operations to place a component



- Use to document existing axis and polar coordinate system better
- Permits arbitrary axis to be defined
- Allows construction of transformation matrices and gain the advantages of using them
- Allows to express an instrument intuitively as a sequence of translations and rotations AND be able to reconstruct absolute positions
- The objective is to allow a full mapping from imageCIF to NeXus and back



- rotation\_angle, polar\_angle, rotate 0 1 0
- azimuthal\_angle, rotate 0 0 1
- distance, translate 0 0 1
- chi, rotate 0 0 1
- phi rotate, 0 1 0
- NeXus polar coordinate system: rotate azimuthal\_angle, rotate polar\_angle, translate by distance

- NeXus stays with the McStas Laboratory coordinate system
- NeXus strongly encourages to use the named and documented NeXus axis
- Allow attributes type, direction in order to support arbitrary axis
- Add aequatorial\_angle as a name to appear in base classes for rotation 1 0 0.
- Add y\_translation (translate 0 1 0) and x\_translation (translate 1 0 0) to base classes.



- Implied: use existing NeXus coordinate system
- dependson attribute pointing to depending axis
- transform field in base classes which becomes a comma separated list of the path to the transformations required to position this component
- Create a special container to hold axis dependencies, NXdependency, to collect the dependencies in one place for easy access. This is what CIF does



```
sample, NXsample
rotation_angle
chi (dependson rotation_angle)
phi (dependson phi)
```



### Transform Option

```
sample, NXsample
rotation_angle
chi
phi
transform = rotation_angle, chi, phi
```



```
sample, NXsample
      rotation angle
      chi
      phi
dependency, NXdependency
      sample/chi =
             sample/rotation angle
      sample/phi =
             sample/chi
      instrument/detector/x translation =
             instrument/detector/distance
      instrument/detector/distance =
             instrument/detector/polar angle
```



entry, NXentry measurement, NXmeasurement positions:NXpositioner om two theta scalars:NXscalar title wavelength images:NXimagedata detector1 mca5



- Refinement of application definitions with communities
- Overhaul of documentation: Manual, NAPI, WWW-site
- Strengthen nxvalidate
- OO base classes?
- Higher level NeXus-APIs?

